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 S1
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                  RD (unique items)
 S13
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14/9/1 (Item 1 from file: 5)
DIALOG(R)File 5:Biosis Previews(R)
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0011817577 BIOSIS NO.: 199900077237

Inhalation challenge testing of latex-sensitive health care workers and the effectiveness of laminar flow HEPA-filtered helmets in reducing rhinoconjunctival and asthmatic reactions

AUTHOR: Laoprasert Nunthaporn; Swanson Mark C; Jones Richard T; Schroeder Darrell R; Yunginger John W (Reprint)

AUTHOR ADDRESS: Allergic Dis. Res. Lab., 406 Guggenheim Build., Mayo Clin., 200 First St. SW, Rochester, MN 55905, USA**USA

JOURNAL: Journal of Allergy and Clinical Immunology 102 (6 PART 1): p

998-1004 Dec., 1998 1998

MEDIUM: print ISSN: 0091-6749

DOCUMENT TYPE: Article
RECORD TYPE: Abstract
LANGUAGE: English

ABSTRACT: Background: There are few data relating latex aeroallergen concentrations to biologic responses in latex-sensitized persons. Objectives: We sought to investigate acceptable latex aeroallergen concentrations below which latex-sensitive health care workers do not experience symptoms and to study the effect of high-efficiency particle arrest (HEPA) -filtered laminar flow helmets in preventing latex-induced symptoms. Methods: Under challenge chamber conditions, latex-sensitive health care workers underwent 7 sequential inhalation challenge tests by donning and discarding either vinyl gloves (challenge 1), low latex-allergen powder-free gloves (challenge 2), or high latex-allergen powdered gloves (challenges 3 to 7) for up to 1 hour. Volunteers wore a laminar flow helmet during all challenges; HEPA filters in the helmet were in place only during challenges 3 and 4. Flow-volume loops, symptom scores, and latex aeroallergen concentrations were measured before and during each test. Results: At 60 minutes, latex aeroallergen concentrations during challenges 3 to 7 (mean, 7600 ng/m3; range, 93 to 54,000 ng/m3) were significantly higher than during challenges 1 or 2 (mean, 65 ng/m3; range, nondetectable to 100 ng/m3) (P < .001). During challenges 5 and 6, mean maximum percent falls in FEV1 (-16% and -11%, respectively) were significantly greater compared with those measured during challenges 3 and 4 (-3% and -1%, respectively) (P = .03). Mean maximum change from baseline symptom scores during challenges 5 and 6 was significantly higher than that during challenges 3 and 4 (P = .006). During challenges with high latex-allergen gloves , 4 volunteers had reproducible FEV1 falls of 20% or greater at cumulative inhaled latex aeroallergen doses ranging from less than 100 ng to 1500 ng. Conclusion: The laminar flow helmets were effective in reducing latex-induced symptoms. Only 1 volunteer exhibited a fall in FEV1 of 20% or greater after a cumulative inhaled latex aeroallergen dose of less than 100 ng, and no volunteer showed a decline in FEV, after exposure to powder-free low allergen gloves .

DESCRIPTORS:

MAJOR CONCEPTS: Allergy--Clinical Immunology, Human Medicine, Medical Sciences

BIOSYSTEMATIC NAMES: Hominidae--Primates, Mammalia, Vertebrata, Chordata, Animalia

ORGANISMS: human (Hominidae) -- health care worker, latex sensitive
COMMON TAXONOMIC TERMS: Animals; Chordates; Humans; Mammals; Primates;
Vertebrates

METHODS & EQUIPMENT: inhalation challenge testing--diagnostic method; laminar flow HEPA-filtered helmets--diagnostic method MISCELLANEOUS TERMS: asthmatic reaction; forced expiratory volume; rhinoconjunctival reaction CONCEPT CODES: 35500 Allergy 34502 Immunology - General and methods BIOSYSTEMATIC CODES: 86215 Hominidae

14/9/2 (Item 2 from file: 5)
DIALOG(R)File 5:Biosis Previews(R)
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0010980885 BIOSIS NO.: 199799614945

The bionic glove: An electrical stimulator garment that provides controlled grasp and hand opening in quadriplegia

AUTHOR: Prochazka Arthur (Reprint); Gauthier Michel; Wieler Marguerite; Kenwell Zoltan

AUTHOR ADDRESS: Div. Neurosci., 507 HMRc, Univ. Alberta, Edmonton, AB T6G 2S2, Canada**Canada

JOURNAL: Archives of Physical Medicine and Rehabilitation 78 (6): p608-614 1997 1997

ISSN: 0003-9993

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DOCUMENT TYPE: Article RECORD TYPE: Abstract LANGUAGE: English

ABSTRACT: Objective: This report describes the operation of the Bionic Glove , a new functional electrical stimulation (FES) device designed to improve the function of the paralyzed hand after spinal cord injury (SCI) or stroke. Design: Signals from a sensor in the glove voluntary wrist movement are used to control FES of muscles either to produce hand-grasp or to open the hand. When the glove is donned, conductive areas on its inside surface automatically make contact with self-adhesive electrodes on the skin. Setting and Patients: This report concerns nine people with SCI who have used the device in their daily lives for up to a year or more. Measurements were made at clinics in Edmonton, Miami, and Chicago as part of a multicenter clinical trial. Outcome Measures and Results: The mean peak force of tenodesis grasp in the nine subjects increased from 2.6N (passive) to 11.3N (glove active). Active force was significantly greater than passive grasp force even when muscles were fatigued after repetitive grasp-release cycles. Most manual tasks improved significantly with the use of the glove , as judged by the number of tasks completed in a minute or the subjects' qualitative ratings of task difficulty. Conclusion: The Bionic Glove can provide significant improvement of hand function in people with C6-C7 SCI.

DESCRIPTORS:

MAJOR CONCEPTS: Methods and Techniques; Nervous System--Neural Coordination; Neurology--Human Medicine, Medical Sciences
BIOSYSTEMATIC NAMES: Hominidae--Primates, Mammalia, Vertebrata, Chordata, Animalia
ORGANISMS: human (Hominidae)
COMMON TAXONOMIC TERMS: Animals; Chordates; Humans; Mammals; Primates;

Vertebrates
MISCELLANEOUS TERMS: BIONIC GLOVE ; CONTROLLED GRASP; ELECTRICAL

MISCELLANEOUS TERMS: BIONIC GLOVE; CONTROLLED GRASP; ELECTRICAL STIMULATOR GARMENT; HAND OPENING; NERVOUS SYSTEM DISEASE; PHYSICAL

REHABILITATION; QUADRIPLEGIA; THERAPEUTIC METHOD CONCEPT CODES:

10511 Biophysics - Bioengineering
12010 Physiology - Exercise and physical therapy
12512 Pathology - Therapy
20501 Nervous system - General and methods
20506 Nervous system - Pathology
BIOSYSTEMATIC CODES:
86215 Hominidae

14/9/3 (Item 1 from file: 155)
DIALOG(R)File 155:MEDLINE(R)
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12507063 PMID: 14510282

Ease of donning of new powder-free non-latex and latex double- glove hole puncture indication systems.

Edlich Richard F; Wind Tyler C; Heather Cynthia L; Thacker John G Plastic Surgical Research Program, University of Virginia Health System, Charlottesville, Virginia, USA. redlich9@attbi.com

Journal of long-term effects of medical implants (United States) 2003,

13 (2) p91-6, ISSN 1050-6934 Journal Code: 9110830

Document type: Journal Article

Languages: ENGLISH
Main Citation Owner: NLM
Record type: Completed

Subfile: HEALTH TECHNOLOGY ASSESSMENT

Cornstarch on surgical gloves is often used as a detackifying agent and donning . During the last century, a lubricant to facilitate glove scientific studies have demonstrated that cornstarch produces tissue injury in literally every part of the body. Because this glove lubricant cannot be removed from the glove , Dr. David Podell, an ophthalmologic surgeon, and his cousin, Howard Podell, a chemical engineer, devised the first powder-free surgical glove that could be donned easily. They coated the inner surface of the surgical glove with a methacrylate polymer lining that was bonded to the natural rubber latex. This special coating acts as a lubricant to facilitate donning with damp, wet, or dry hands. In our earlier experimental studies, we confirmed that these polymer-lined latex gloves could be donned with either wet or dry hands. More recently, the polymer-coated latex gloves were incorporated into a double- glove hole puncture indication system that accurately detected glove holes in the presence of fluid. Because this discovery has been expanded into the development of a non-latex double- glove hole puncture indication system, we have expanded our biomechanical performance studies to examine the forces of the latex and non-latex glove hole puncture donning indication systems. The maximum donning forces recorded for the non-latex undergloves were significantly lower than those encountered by the same respective sizes of the latex underglove. The 1donning forces of the thin Biogel Super-Sensitive outer gloves were remarkably similar forces of the Biogel Indicator undergloves. The thicker to the **donning** Biogel outer gloves encountered greater donning forces than that noted for the Biogel Super-Sensitive outer gloves . The donning recorded for the non-latex outer gloves were remarkably similar to those noted for the latex Biogel outer gloves . Because the results of this biomechanical performance study demonstrated that the latex and non-latex double- glove hole puncture indication systems can be easily donned by surgeons using relatively low donning forces , this study provides convincing evidence that these double- glove hole puncture indication systems can be used in all surgical procedures.

Tags: Human; Support, Non-U.S. Gov't

Descriptors: Equipment Design; * Gloves , Surgical; Biomechanics; Latex;

Needlestick Injuries--prevention and control--PC; Starch CAS Registry No.: 0 (Latex); 9005-25-8 (Starch)

Record Date Created: 20030926
Record Date Completed: 20031016

14/9/4 (Item 2 from file: 155)

DIALOG(R) File 155: MEDLINE(R)

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12423100 PMID: 12825744

Reducing accidental injuries during surgery.

Edlich Richard F; Wind Tyler C; Hill Lisa G; Thacker John G; McGregor Walter

Plastic Surgery Research Program, University of Virginia Health System, Charlottesville, Virginia, USA. redlich9@attbi.com

Journal of long-term effects of medical implants (United States) 2003,

13 (1) p1-10, ISSN 1050-6934 Journal Code: 9110830

Document type: Journal Article

Languages: ENGLISH

Main Citation Owner: NLM Record type: Completed

Subfile: HEALTH TECHNOLOGY ASSESSMENT

Extensive clinical investigations have demonstrated that double- gloves blunt-tipped surgical needles dramatically reduced the risk of accidental injuries during surgery. During the last decade, double- glove hole puncture indication systems have been developed that reduce the clinical risk of accidental needlestick injuries as well as detect the presence of glove hole puncture in the presence of fluids. When the outer is punctured, the colored underglove becomes apparent through the translucent outer glove , necessitating glove removal, hand washing, and donning of another double- glove hole puncture Indicator system. This article presents the first biomechanical performance study that documents the puncture resistance of blunt surgical needles in latex and nonlatex single gloves and double- glove hole puncture indication systems. The technique for measuring glove puncture resistance simulates the standard test for material resistance to puncture outlined by the American Society for Testing and Materials. The maximum puncture resistance force was measured by the compression load cell and recorded in grams with a strip chart recorder. Ten puncture resistance measurements for the taper point needle, blunt taper point needle, and blunt needle were taken from five samples of the Biogel Indicator underglove, Biogel Super-Sensitive glove , Biogel Skinsense N Universal underglove, and , Biogel Skinsense Polyisoprene glove ; and the Biogel, Biogel Super-Sensitive, and Biogel Skinsense Polyisoprene double- glove hole puncture indication systems. The magnitude of puncture resistance forces recorded was influenced by several factors: glove material, number of glove layers, and type of surgical needle. For each type of curved surgical needle, the resistance to needle penetration by the nonlatex gloves was significantly greater than those encountered by the latex materials. The resistance to needle puncture of all three doublesystems was significantly greater than that of either the nonlatex or latex underglove or outer glove. The taper point needle encountered the lowest puncture resistance forces in the five single gloves and the systems. Blunting the sharp end of the taper point three double- glove needle markedly increased its resistance to glove puncture in the five single gloves and five double- glove systems. The blunt-point surgical needle elicited the greatest needle penetration force in all of the

single and double- glove systems.

Tags: Human

Descriptors: Accidents, Occupational--prevention and control--PC; * Gloves , Surgical; *Intraoperative Complications--prevention and control--PC; *Materials Testing; *Needles; *Surgery; *Wounds and Injuries --prevention and control--PC; Equipment Design; Needlestick Injuries --prevention and control--PC

Record Date Created: 20030626 Record Date Completed: 20030804

14/9/5 (Item 1 from file: 6)

DIALOG(R) File 6:NTIS

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1815219 NTIS Accession Number: N94-30210/6

Tactility as a Function of Grasp Force : Effects of Glove ,

Bishu, R. R.; Bronkema, L. A.; Garcia, D.; Klute, G.; Rajulu, S. National Aeronautics and Space Administration, Houston, TX. Lyndon B. Johnson Space Center.

Corp. Source Codes: 019042004; ND185000

Report No.: NAS 1.60:3474; S-761; NASA-TP-3474

May 94 23p

Languages: English

Journal Announcement: GRAI9418; STAR3208

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NTIS Prices: PC A03/MF A01

Country of Publication: United States

One of the reasons for reduction in performance when gloves are donned is the lack of tactile sensitivity. It was argued that grasping force for a weight to be grasped will be a function of the weight to be lifted and the hand conditions. It was further reasoned that the differences in for various hand conditions will be a correlate of the grasping force tactile sensitivity of the corresponding hand conditions. The objective of this experiment, therefore, was to determine the effects of glove type, pressure, and weight of load on the initial grasping force and stable grasping force . It was hypothesized that when a person grasps an object, he/she grasps very firmly initially and then releases the grasp slightly after realizing what force is needed to maintain a steady grasp. This would seem to be particularly true when a person is wearing a glove and has lost some tactile sensitivity and force feedback during the grasp. Therefore, the ratio of initial force and stable force and the stable itself would represent the amount of tactile adjustment that is made when picking up an object, and this adjustment should vary with the use of gloves . A dynamometer was fabricated to measure the grasping ; the tests were performed inside a glove box. Four female and four male subjects participated in the study, which measured the effects of four variables: load effect, gender effect, glove type, and pressure variance. The only significant effects on the peak and stable force were caused by gender and the weight of the load lifted. Neither gloves nor pressure altered these forces when compared to a bare-handed condition, as was suspected before the test. It is possible that gloves facilitate in holding due to coefficient of friction while they deter in peak grasp strength .

Descriptors: Astronaut performance; *Extravehicular activity; * Gloves; *Human factors engineering; *Manual control; *Tactile discrimination;

Coefficient of friction; Loads (Forces); Sex; Space suits Identifiers: NTISNASA Section Headings: 84GE (Space Technology--General); 95E (Biomedical Technology and Human Factors Engineering--Life Support Systems); Technology and Human Factors Engineering--Human Factors (Biomedical Engineering) 14/9/6 (Item 1 from file: 34) DIALOG(R) File 34:SciSearch(R) Cited Ref Sci (c) 2004 Inst for Sci Info. All rts. reserv. 04461095 Genuine Article#: TE257 Number of References: 38 Title: INTERACTION OF SIGNAL WORD AND COLOR ON WARNING LABELS - DIFFERENCES IN PERCEIVED HAZARD AND BEHAVIORAL COMPLIANCE Author(s): BRAUN CC; SILVER NC Corporate Source: UNIV IDAHO, DEPT PSYCHOL/MOSCOW//ID/83844; UNIV NEVADA, DEPT PSYCHOL/LAS VEGAS//NV/89154 * Journal: ERGONOMICS, 1995, V38, N11 (NOV), P2207-2220 ISSN: 0014-0139 Document Type: ARTICLE Language: ENGLISH Geographic Location: USA Subfile: SocSearch; SciSearch; CC ENGI--Current Contents, Engineering, Technology & Applied Sciences; CC SOCS--Current Contents, Social & Behavioral Sciences Journal Subject Category: ERGONOMICS Abstract: Previous research has examined the connoted hazard of various colour and signal welds separately. The purpose of the present research was to examine the interaction of signal words and colours. Two separate experiments examined the influence of colour on perceptions of hazard and on compliance to printed warnings. In experiment 1, a sample of 30 undergraduates rated the perceived hazard of signal words printed in specific hazard colours. Results indicated that the level of hazard varied as a function of the signal word and the colour in which it was presented. Of the colours used, red conveyed the highest level of perceived hazard followed by orange, black, green and blue. More importantly, it was noted that a signal word such as DEADLY connoted less hazard when printed in green than in red ink. Experiment 2 examined the effect of colour on compliance with printed warnings. Sixty-five undergraduates interacted with a pool-water test kit and a two-part adhesive. The warning on each product was factorial for colour (i.e. red, green and black). Behavioural compliance was assessed by indicating if subjects donned protective gloves as directed by the warning. The data indicated that warnings printed in red resulted in a higher proportion of compliant behaviour than green and black combined. Implications for warning design are discussed. Descriptors -- Author Keywords: SAFETY; WARNINGS; COLORS; SIGNAL WORDS Identifiers -- KeyWords Plus: STRENGTH Cited References: CORELDRAW VERSION 3, 1992 ANSI, 1991, AM NAT STAND PROD SA COMM INT ECL, 1971, V15, PUBL

(B) *

INT STAND ORG, 1984, 3464 INT STAND SOC AUT ENG, 1987, J115JAN87 WEST PRINT DIV, 1981, WEST PROD SAF LAB HD ARETZ AJ, 1982, P455, 26TH P HUM FACT SOC BRAUN CC, 1995, V15, P179, INT J IND ERGONOM BRESNAHAN TF, 1975, P17, PROFESSIONAL SAF JAN CALHOUN GL, 1981, P127, 25TH P HUM FACT SOC CASALI JG, 1988, V7, P31, BEHAVIOUR INFORMATIO CHAPANIS A, 1994, V37, P265, ERGONOMICS

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14/9/7 (Item 1 from file: 350)
DIALOG(R) File 350: Derwent WPIX

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012734452

1200 ×

WPI Acc No: 1999-540569/199945

XRAM Acc No: C99-157864 XRPX Acc No: N99-400661

Powder free glove exhibiting minimal discoloration/stickiness after sterilization by irradiation

Patent Assignee: ALLEGIANCE CORP (ALLE-N); ALLEGIANCE HEALTHCARE CORP (ALLE-N)

Inventor: BOURNE G; MOCERI T A; YEH Y T

Number of Countries: 027 Number of Patents: 009

Patent Family:

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Pat	tent No	Kind	Date	App	plicat No	Kind	Date	Week	
WO	9943739	A1	19990902	WO	99US3693	A	19990219	199945	В
ΑU	9927764	A	19990915	ΑU	9927764	A	19990219	200004	
ΕP	979251	A1	20000216	EΡ	99908302	Α	19990219	200014	
				WO	99US3693	A	19990219		
CN	1256702	A	20000614	CN	99800182	Α	19990219	200048	
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JP	2002503138	W	20020129	JP	99543690	A	19990219	200211	
				WO	99US3693	A	19990219		
ΑU	755975	В	20030102	ΑU	9927764	A	19990219	200319	

Priority Applications (No Type Date): US 9832632 A 19980227

Patent Details:

Patent No Kind Lan Pg Main IPC Filing Notes

WO 9943739 A1 E 23 C08J-005/02

Designated States (National): AU CA CN JP KR SG

Designated States (Regional): AT BE CH CY DE DK ES FI FR GB GR IE IT LU MC NL PT SE Based on patent WO 9943739 AU 9927764 Based on patent WO 9943739 EP 979251 A1 E Designated States (Regional): AT BE CH CY DE DK ES FI FR GB GR IE IT LI LU MC NL PT SE CN 1256702 Α C08J-005/02 A61B-019/04 TW 400224 Α A41D-019/015 US 6195805 Bl C08J-005/02 KR 2001020302 A Based on patent WO 9943739 · JP 2002503138 W 22 A61B-019/04 В C08J-005/02 Previous Publ. patent AU 9927764 AU 755975 Based on patent WO 9943739 Abstract (Basic): WO 9943739 Al NOVELTY - Powder free glove exhibiting minimal discoloration/stickiness after sterilization by irradiation is fabricated from neoprene copolymer having specified tensile strength , stress, elongation at break and stickiness. DETAILED DESCRIPTION - A powder free glove is fabricated from neoprene copolymer having a tensile strength of at least 2500 psi, a stress at 500% no greater than 1015 psi, an elongation to break of at least 650% and a stickiness no greater than 0.2 lbs. INDEPENDENT CLAIMS are also included for: (1) a powder-free glove formulated from a neoprene copolymer of chloroprene and 2,3-dichlorobutadiene having a tensile stress of at least 2500 psi; and (2) a process for making the glove , the process comprising: (i) dipping a former into a coagulant dispersion to deposit a coagulant layer on the former; (ii) dipping the former with the deposited layer into a neoprene copolymer latex formulation to produce a second layer comprising coagulated neoprene on it; (iii) leaching the former with water; (iv) dipping the second layer of coagulated neoprene copolymer into a powdered slurry comprised of a surfactant, powder, silicone and water; (v) curing the layers on the former; (vi) stripping the glove from the former; (vii) turning the glove so that the inner surface of the glove is on the exterior of the glove; (viii) chlorinating the **glove** to remove powder; (ix) rinsing the glove with water; (x) lubricating the glove; (xi) drying the glove; (xii) turning the glove so that the inner surface of the glove is on the interior of the glove; and (xiii) drying the glove . USE - The gloves have medical applications. ADVANTAGE - The gloves comprise hypoallergenic medical gloves and can be donned easily without the use of powdered donning agents and retain puncture resistance, tensile strength , stress at 500% and elongation to break after post-processing by chlorination and sterilization by irradiation. The gloves also exhibit minimal discoloration and minimal stickiness to packing materials or to themselves. pp; 23 DwgNo 0/0 Technology Focus: TECHNOLOGY FOCUS - POLYMERS - Preferred Glove : The neoprene copolymer is a copolymer of chloroprene and 2,3-dichloro-1,3-butadiene. The glove has a puncture resistance of greater than 2 lbs, the %

7. Feb. 10

change in the yellowness index measured according to ASTM D1925 is no greater than 15%. The neoprene copolymer contains 25-55 (especially 40) wt.% Cl, has a stress at 500% of no greater than 1015 psi and an elongation at break of at least 650%. Preferred Process: The process comprises additional steps after final drying of packing the glove and irradiating with an electron beam. The lubricant is comprised of cetylpyridinium chloride and water or nonionic surfactants and/or ionic surfactants or surfactant and water-soluble polymer combination. The glove is irradiated at a minimum dose to meet SAL of 106.

Extension Abstract:

EXAMPLE - Sterile powder-free gloves were made by first preheating a glove former in an oven at 100-200 degreesF. The former was dipped into alcohol-based coagulant dispersion, comprising 50-70 wt.% methanol, 25-40 wt.% calcium nitrate and 5-15 wt.% calcium carbonate, at less than 110 degreesF. The glove former was dried in air. The former was dipped into compounded neoprene rubber copolymer latex, comprising copolymer of chloroprene and 2,3-dichloro-2,3-butadiene, maintained at 70-85 degreesF. The former was leached for 5-8 minutes in water at 100-150 degreesF, dipped into powder slurry comprising 0.02-0.1 wt.% stabilizers, 10-20 wt.% crosslinked corn starch powders, 0.5-1.5 wt.% silicone and water and optionally wetting and antimicrobial agents. The gloves were beaded using a beader and cured while on the former at 330 degreesF for 20-30 minutes. The gloves were cooled and stripped from the former. The powdered gloves were subjected to post-processing treatment comprising turning the gloves inside out, chlorination, neutralization, rinsing, lubrication and drying to produce powder-free gloves .

Title Terms: POWDER; FREE; GLOVE; EXHIBIT; MINIMUM; DISCOLOUR; STICKY; AFTER; STERILE; IRRADIATE

Derwent Class: A12; A83; A96; D22; E13; H07; P21; P31; P32; P34
International Patent Class (Main): A41D-019/015; A61B-019/04; C08J-005/02
International Patent Class (Additional): A41D-019/00; A41D-019/04;
A61F-013/10; A61L-002/08; A61L-031/00; C08J-005/18; C08L-011/00;
C08L-011/02; C08L-011-00

File Segment: CPI; EngPI

Manual Codes (CPI/A-N): A04-B08; A12-C02A; A12-V03D; D09-C04D; E07-D04A; H07-X

Chemical Fragment Codes (M3):

- *01* H6 H602 H683 H7 H724 M210 M214 M231 M250 M281 M320 M416 M424 M740 M782 M904 M905 N105 Q120 Q130 R01079-K R01079-M
- *02* A220 A940 C108 C307 C510 C730 C801 C802 C803 C804 C807 M411 M424 M740 M782 M904 M905 M910 N105 Q120 Q130 R01905-K R01905-M
- *03* A220 A940 C106 C108 C530 C730 C801 C802 C803 C805 C807 M411 M424 M740 M782 M904 M905 M910 N105 Q120 Q130 R01278-K R01278-M R05243-K R05243-M
- *04* H4 H401 H481 H8 M210 M211 M272 M281 M320 M416 M424 M620 M740 M782 M904 M905 M910 N105 Q120 Q130 R00270-K R00270-M
- *05* H6 H602 H608 H683 H689 H7 H724 M280 M314 M321 M331 M342 M363 M391 M416 M424 M740 M782 M904 M905 N105 Q120 Q130 R20388-K R20388-M Polymer Indexing (PS):

<01>

- *001* 018; H0022 H0011; R01079 G0828 G0817 D01 D12 D10 D51 D54 D56 D58 D69 D84 Cl 7A; G0839 G0828 G0817 D01 D12 D10 D51 D54 D56 D58 D69 D84 Cl 7A; H0124-R; S9999 S1025 S1014; P0328
- *002* 018; ND01; Q9999 Q7078 Q7056; B9999 B5323 B5298 B5276; N9999 N6871 N6655; K9790-R; B9999 B4171 B4091 B3838 B3747; B9999 B3907 B3838 B3747; B9999 B4273 B4240; ND07; N9999 N6473 N6440; N9999 N7318 N6655; K9723; N9999 N6699 N6655; N9999 N6882 N6655; N9999 N6780-R N6655; N9999 N6279 N6268; N9999 N6337-R; B9999 B4182 B4091 B3838

B3747; K9814 K9803 K9790 *003* 018; D01 D11 D10 D23 D22 D31 D76 D41 D50 D94 F16 D61-R Cl 7A; A999 A340-R Derwent Registry Numbers: 0270-U; 1079-U; 1278-U; 1905-U Specific Compound Numbers: R01079-K; R01079-M; R01905-K; R01905-M; R01278-K ; R01278-M; R05243-K; R05243-M; R00270-K; R00270-M; R20388-K; R20388-M Key Word Indexing Terms: 140524-0-0-0-CL 3847-0-0-CL 89827-0-0-CL 15-0-0-CL 57648-0-0-0-CL (Item 2 from file: 350) DIALOG(R) File 350: Derwent WPIX (c) 2004 Thomson Derwent. All rts. reserv. 009849227 **Image available** WPI Acc No: 1994-129083/199416 XRAM Acc No: C94-059583 XRPX Acc No: N94-101281 Device for donning gloves for handling radioactive material - has solenoid valve operated suction device connected to suction hole at bottom of container with hole at top for fitting glove and inserting hand Patent Assignee: DORYOKURO KAKUNENRYO KAIHATSU (DORY) Number of Countries: 001 Number of Patents: 001 Patent Family: Applicat No Kind Patent No Kind Date Date Week 19940318 JP 92225902 19920825 199416 B JP 6075092 Α Α Priority Applications (No Type Date): JP 92225902 A 19920825 Patent Details: Main IPC Patent No Kind Lan Pq Filing Notes JP 6075092 3 G21F-003/035 Α Abstract (Basic): JP 6075092 A Device cylindrical and transparent glove donning container having upper end opening for donning glove . A suction device is connected to the suction hole at the bottom of the container. A solenoid valve operates interlocking with the suction device and a switch operates the suction device and the solenoid valve. A pressure gauge is provided for detection of pressure change in the container. USE/ADVANTAGE - The device is used for fitting gloves for handling radioactive material in nuclear power plant, etc. The device can avoid contamination of gloves from using ones. In medical use, a doctor can equip himself without aid of assistant without contamination. Dwg.2/2 Title Terms: DEVICE; DONNING; GLOVE; HANDLE; RADIOACTIVE; MATERIAL; SOLENOID; VALVE; OPERATE; SUCTION; DEVICE; CONNECT; SUCTION; HOLE; BOTTOM ; CONTAINER; HOLE; TOP; FIT; GLOVE; INSERT; HAND Derwent Class: K07; P31 International Patent Class (Main): G21F-003/035 International Patent Class (Additional): A61B-019/04; G21F-007/053 File Segment: CPI; EngPI Manual Codes (CPI/A-N): K07-A

14/9/9 (Item 3 from file: 350) DIALOG(R) File 350: Derwent WPIX (c) 2004 Thomson Derwent. All rts. reserv.

(B# W

Image available 008913332 WPI Acc No: 1992-040601/199205 XRPX Acc No: N92-031245 Device to apply elastic gloves - has cylinders which hold elastic gloves and form air tight seal Patent Assignee: SULLIVAN J L (SULL-I) Inventor: SULLIVAN J L Number of Countries: 001 Number of Patents: 001 Patent Family: Patent No Applicat No Kind Week Kind Date 19920107 US 91656793 Α 19910219 199205 B US 5078308 Α Priority Applications (No Type Date): US 91656793 A 19910219 Abstract (Basic): US 5078308 A The device may be mounted to any flat surface. Glove donning cylinders (100) hold elastic gloves securely in place and form an air tight seal between cylinder and elastic glove . When a hand is inserted into the cylinder, sealed with an elastic glove , air in the cylinder is forced out through a one-way check valve (400). When the hand is retracted slightly or fully, the elastic glove is pulled into the cylinder by the vacuum developed below the glove to expand larger than a hand. The user may then insert a hand friction free and disengages the glove from the cylinder by rolling the cuff up and off the upper edge (130) of the cylinder. When the air tight seal is broken, the glove deflates rapidly and conforms to the shape of the hand with no air pockets at the finger tips. If the vacuum indicator (500) indicates a loss of vacuum in the cylinder, the glove may have a hole through which bodily fluids can pass. USE - To inflate and detect pinhole size leaks in elastic gloves using no internal or external energy sources. (9pp Dwg.No.4/4)Title Terms: DEVICE; APPLY; ELASTIC; GLOVE; CYLINDER; HOLD; ELASTIC; GLOVE ; FORM; AIR; TIGHT; SEAL Derwent Class: P27 International Patent Class (Main): A47G-025/90 File Segment: EngPI (Item 4 from file: 350) 14/9/10 DIALOG(R) File 350: Derwent WPIX (c) 2004 Thomson Derwent. All rts. reserv. 003782261 WPI Acc No: 1983-778488/198340 XRAM Acc No: C83-095073 XRPX Acc No: N83-174764 Flexible surgical glove - made from soft low modulus non crystalline segmented polyurethane Patent Assignee: DESERET MED INC (DESR); WARNER-LAMBERT CO (WARN); DESERET MEDICAL INC (DESE-N) Inventor: MCGARY C W; PASCARELLA V J; RHODES D R; TALLER R A Number of Countries: 006 Number of Patents: 008 Patent Family: Applicat No Patent No Kind Date Kind Date Week 19830928 EP 83301284 EP 89780 Α Α 19830309 198340 B JP 58165836 Α 19830930 198345

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19840731 US 82357912

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19820315 198433

198542 CA 1193788 A 19850917 198821 EP 89780 B 19880525 198827 DE 3376733 G 19880630 B 19920311 JP 8341608 Α 199214 JP 92014125 19830315 B2 19940615 EP 83301284 Α 19830309 199423 EP 89780 Priority Applications (No Type Date): US 82357912 A 19820315 Cited Patents: BE 624888; CH 452888; EP 4116; GB 993339; No-SR.Pub; 01Jnl.Ref Patent Details: Patent No Kind Lan Pg Main IPC Filing Notes A E 41 Designated States (Regional): DE FR GB B E Designated States (Regional): DE FR GB JP 92014125 В 14 B2 E 20 A61B-019/04 EP 89780 Designated States (Regional): DE FR GB

Abstract (Basic): EP 89780 A

Flexible glove for use by surgeons and others is formed from a polyurethane having a 100% modulus of less than ca. 250 psi, initial tensile set less than ca. 30% and a tensile strength of 3500-6500 psi.

The polyurethane is pref. a segmented polyurethane in which the percentage of hard segment is 14-25% and the degree of crosslinking is ca. 5000-30,000 Mc. The polyurethane is esp a reaction prod. of an aromatic or alicyclic diisocyanate, a short chain diol extender, a 500-5000 mol wt. long chain diol and polyhydroxy cross linking agent. The prod. pref. contains 13-23% of polyisocyanate chosen from, 4,4'-diphenylmethane diisocyanate, TDI, isophorone diisocyanate and methylene bis(4-cyclohexyl isocyanate); 0.5-3.0% of a short chain diol extender contg. up to 6C; and a long chain diol comprising a polyester diol or mixt. of these chosen from poly(ethylene adipate)diol, polycaprolactone diol or a blend of these. The inside surface of the glove intended to be worn against the skin may contain an embedded solid lubricant.

The **gloves** are easily **donned** and comfortable to wear, and do not contain additives likely to cause dermatitis or allergic reactions. Abstract (Equivalent): EP 89780 B

A flexible **glove** suitable for use by surgeons and others, wherein the **glove** is formed of a material which comprises a polyurethane having a 100% modulus less than approximately 17.6 kg/cm2 (250 psi), initial tensile set less than approximately 30% and tensile **strength** of approximately from 246 to 457 kg/cm2 (3500 to 6500 psi), **measurements** being made in accordance with ASTM 0412-68. (18pp) Abstract (Equivalent): US 4463156 A

Non-crystalline segmented polyurethane with a 100% modulus less than about 250 psi, initial tensile set less than about 30%, and tensile strength about 3500-6500 psi is obtd. by balancing the hard segment content and the degree of cross linking (14-25 wt.% hard segment material, Mr 5,000-30,000 per crosslink). Pref. polyurethane is obtd. from aromatic or alicyclic diisocyanates, short chain diol extenders, a long chain diol (Mr 500-5000) and a polyol crosslinking agent.

USE - The prods. are used to mfr. soft, flexible **gloves** for surgical use. (11pp)e

Title Terms: FLEXIBLE; SURGICAL; GLOVE; MADE; SOFT; LOW; MODULUS; NON; CRYSTAL; SEGMENT; POLYURETHANE

Derwent Class: A25; A96; P21; P31

🚁 International Patent Class (Main): A61B-019/04

14/9/11 (Item 1 from file: 144)
DIALOG(R)File 144:Pascal
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12822260 PASCAL No.: 97-0038815

Ease of donning commercially available powder-free surgical gloves FISHER M D; NEAL J G; KHEIR J N; WOODS J A; THACKER J G; EDLICH R F Department of Plastic Surgery, University of Virginia School of Medicine, Charlottesville, Virginia, United States; Department of Mechanical and Aerospace Engineering, University of Virginia, Charlottesville, Virginia, United States; Department of Biomedical Engineering, University of Virginia School of Medicine, Charlottesville, Virginia, United States Journal: Journal of biomedical materials research, 1996, 33 (4) 291-295 ISSN: 0021-9304 CODEN: JBMRBG Availability: INIST-13764;

354000060998580090 No. of Refs.: 6 ref.

Document Type: P (Serial) ; A (Analytic) Country of Publication: United States Language: English

There are a wide variety of powder-free gloves that can now be used by surgeons. The purpose of this study was to quantify the forces required to don these powder-free surgical gloves. The lowest donning forces for wet hands was encountered with powder-free gloves coated with a hydrogel polymer. In addition, the hydrogel coated gloves exhibited the least increase in donning forces from dry hands to wet hands. While greater forces were encountered with the other commercially available powder-free gloves than the hydrogel coated gloves, they all could be safely donned on dry hands without tearing.

English Descriptors: Quantitative analysis; Force measurement; Glove;
Surgical equipment; Hydrogel; Polymer; Coated material; Lubricant; Starch
; Comparative study; Experimental design; Clinical trial

French Descriptors: Analyse quantitative; Mesure **force**; Gant; Equipement chirurgical; Hydrogel; Polymere; Materiau revetu; Lubrifiant; Amidon; Etude comparative; Plan experience; Essai clinique

Classification Codes: 002B26N

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14/9/12 (Item 1 from file: 95)

DIALOG(R) File 95:TEME-Technology & Management (c) 2004 FIZ TECHNIK. All rts. reserv.

01363098 19991104915

Biomechanical performance of examination gloves (Biomechanische Leistung von Untersuchungshandschuhen aus Latex, Nitril oder PVC)
Jackson, EM; Williams, FM; Neal, JG; Suber, F; Thacker, JG; Edlich, RF Univ. of Virginia, Charlottesville, USA
Journal of Biomedical Materials Research, v48, n4, pp572-577, 1999
Document type: journal article Language: English
Record type: Abstract
ISSN: 0021-9304

ABSTRACT:

(B) *

new powder-free commercially available synthetic examination gloves to that of commercially available powder-free latex examination gloves. The synthetic gloves were significantly thinner than the latex gloves.

Despite the decreased thickness, all three nitrile gloves, as well as the polyvinylchloride glove, exhibited a greater resistance to glove puncture. The glove donning forces varied considerably among all gloves, and wet donning forces were greater than dry donning forces. Under dry conditions, the donning forces for the synthetic gloves were less than or equal to the forces for the latex gloves. Because of their increased puncture resistance and similar donning forces, synthetic gloves are a safe alternative to latex examination gloves.

The purpose of the study was to compare the biomechanical performance of

DESCRIPTORS: PROTECTIVE GLOVE; POLY VINYL CHLORIDE; NITRILE; PUNCTURE RESISTANCE; TEST DEVICES; THICKNESS MEASUREMENT; BIOCOMPATIBLE MATERIALS; BIOMECHANICS
IDENTIFIERS: DISK CRIMINATOR; Untersuchungs-Handschuh; Biomechanik;

14/9/13 (Item 2 from file: 95)
DIALOG(R)File 95:TEME-Technology & Management
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01336865 F99080022982

Latex-Handschuh

Biomechanical performance fo orthopedic gloves (Biomechanische Leistung orthopaedischer Handschuhe)
Jackson, EM; Neal, JG; Williams, FM; Stern, CA; Suber, F; Thacker, JG; Edlich, RF
Univ. of Virginia School of Medicine, Charlottsville, USA
Journal of Biomedical Materials Research, v48, n2, pp193-198, 1999
Document type: journal article Language: English
Record type: Abstract
ISSN: 0021-9304

ABSTRACT:

The purpose of the study was to compare the biomechanical performance of commercially available orthopedic gloves to that of a single surgical glove, as well as a double glove system. The orthopedic gloves were found to be thicker than the single surgical glove. This increased thickness of the orthopedic glove was associated with a greater resistance to glove puncture. The thickest orthopedic gloves also had reduced tactile sensitivity when compared to the single surgical glove. In addition, the glove donning forces and glove hydration rates varied considerably. These latter biomechanical performance parameters were

not significantly related to glove thickness. The double glove system tested in the study had similar performance characteristics in regard to many of the orthopedic gloves . The glove donning forces for the double glove systems were the lowest of the gloves tested. In addition, the double glove systems displayed the greatest resistance to glove hydration of the **gloves** tested. Their performance in the **glove** hydration tests and the **force** required to don the double **glove** systems were much more desirable than any of the orthopedic gloves . The results of the study indicate that the double glove systems may provide a desirable alternative to the use of the single orthopedic gloves .

DESCRIPTORS: BIOMECHANICS; WATER CONTENT; SURGERY; CRACKING--FRACTURING; THICKNESS; TEST DEVICES; PULL STRENGTH; FORCE MEASUREMENT IDENTIFIERS: HANDSCHUH--(ORTHOPAEDIE); LATEX HANDSCHUH; TASTVERMOEGEN; DRUCK AESTHESIOMETER; FLUID ALARM SYSTEM; DISK CRIMINATOR; Handschuh (Orthopaedie); Biomechanik; Rissfestigkeit

14/9/14 (Item 3 from file: 95) DIALOG(R) File 95: TEME-Technology & Management (c) 2004 FIZ TECHNIK. All rts. reserv.

01291225 F99030076982

Ease of donning commercially available latex examination gloves (Leichtigkeit, mit der kommerziell verfuegbare Latexhandschuhe anzuziehen

Cote, SJ; Fisher, MD; Kheir, JN; Paull, RB; Neal, JG; Jackson, EM; Suber, F ; Thacker, JG; O'Keefe, JS; Edlich, RF

Univ. of Virginia, Charlottesville, USA

Journal of Biomedical Materials Research, v43, n3, pp331-337, 1998 Document type: journal article Language: English

Record type: Abstract

ISSN: 0021-9304

ABSTRACT:

CON W

There are a wide variety of latex examination gloves now available for use by health care providers. A prospective randomized trial was completed to quantify the forces required to don a sample of seven cornstarch-lubricated gloves and 13 powder-free latex examination gloves . The data collected was analyzed by a 20 x 2 general factorial ANOVA, as well as two 1-way ANOVAs using a least significance difference post hoc test. Some powder-free gloves can be easily donned with dry or wet hands without tearing with forces comparable to those encountered with powdered gloves . With the advent of these powder-free examination gloves , powdered gloves can now be abandoned, protecting health professionals and patients from the dangers of absorbable dusting powders. Despite the dangers of the absorbable dusting powders and the Food and Drug Administration's requirement for labeling examination glove boxes, some manufacturers of powdered examination gloves do not appropriately label their boxes with a warning to the health professional and patient of the presence of powder.

DESCRIPTORS: SLIDING MATERIALS; FORCE MEASUREMENT; PROTECTIVE CLOTHING; HEALTH CARE; CORN STARCH IDENTIFIERS: LATEXHANDSCHUHE; PUDER; PUDERFREIE HANDSCHUHE; KLEINSTE SIGNIFIKANTE DIFFERENZEN; Untersuchungshandschuh; Latex; Puder; Kraftmessung

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(Item 2 from file: 2)
   DIALOG(R) File
                    2:INSPEC
    (c) 2004 Institution of Electrical Engineers. All rts. reserv.
              INSPEC Abstract Number: B9402-8380-008, C9402-3250-004
    Title: Utilization of stepping motors in the realization of a prototype of
   perceptive glove with feedback force for telerobotics
      Author(s): Milanesi, S.; Rovetta, A.; Sala, R.; Togno, A.; Wen, X.
      Author Affiliation: Dept. of Mech., Politecnico of Milano, Italy
      Conference Title: ISIE'93 - Budapest. IEEE International Symposium on
    Industrial Electronics. Conference Proceedings (Cat.No.93TH0540-5)
    634 - 7
      Publisher: IEEE, New York, NY, USA
      Publication Date: 1993 Country of Publication: USA
      ISBN: 0 7803 1227 9
      U.S. Copyright Clearance Center Code: 0 7803 1227 9/93/$3.00
      Conference Sponsor: IEEE; EPRI; Hungarian Electrotech. Assoc.; Hungarian
    Acad. Sci.; et al
      Conference Date: 1-3 June 1993
                                          Conference Location: Budapest, Hungary
                            Document Type: Conference Paper (PA)
      Language: English
      Treatment: Practical (P)
                  Force feedback is a basic element in realizations for
   telemanipulation and virtual reality. In telemanipulation, tactile but especially force information permits the remote operator to carry out efficiently operations which would otherwise be difficult to perform;
    nevertheless it permits a better simulation and interaction of virtual environment in the case of virtual reality. A system for grasping objects
was projected and realized in a robotics laboratory. The operator wearing
         glove
                 drives a mechanical hand, having a force
                                                               sensor on his own
    а
    hand. This increases the performance of the telemanipulation system. The
    whole project is explained with particular attention to the control system
    of stepping motors used for force feedback.
                                                   (6 Refs)
      Subfile: B C
      Descriptors: data gloves; electric control equipment; feedback; force
    control; robots; stepping motors; telecontrol; virtual reality
      Identifiers: force control; stepping motors; perceptive glove;
    telerobotics; telemanipulation; virtual reality; laboratory; performance;
    project; force feedback
      Class Codes: B8380 (Control gear and apparatus); B8340 (Small and
    special purpose electric machines); C3250 (Telecontrol and telemetering
    components); C3120F (Force, torque and work); C3390 (Robotics); C3260B (
    Electric equipment); C5540B (Interactive-input devices); C7420 (Control
    engineering)
                (Item 1 from file: 155)
    DIALOG(R) File 155: MEDLINE(R)
(c) format only 2004 The Dialog Corp. All rts. reserv.
               PMID: 10595890
      Biomechanical performance of powder-free examination gloves.
      Fisher M D; Reddy V R; Williams F M; Lin K Y; Thacker J G; Edlich R F
      Department of Plastic Surgery, University of Virginia School of Medicine,
    Charlottesville 22908, USA.
      Journal of emergency medicine (UNITED STATES)
                                                            Nov-Dec 1999, 17 (6)
     p1011-8, ISSN 0736-4679
                                Journal Code: 8412174
      Document type: Clinical Trial; Journal Article
      Languages: ENGLISH
      Main Citation Owner: NLM
      Record type: Completed
      Subfile:
                 INDEX MEDICUS
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Biomechanical performance studies were undertaken for powder-free, latex and nitrile examination gloves. Using standardized tests, examination glove performance was judged by measuring glove thickness, glove puncture , glove tape adhesion force , glove donning force , glove stiffness, and immediate unrecovered stretch. Even though the nitrile examination gloves were thinner than the latex examination gloves, they exhibited a greater puncture resistance. In addition, tape adherence to the N-Dex nitrile glove was the lowest. Moreover, measurements of the handling characteristics of the nitrile examination gloves demonstrated that they are an acceptable alternative to latex examination gloves. While these studies demonstrate the superiority of the nitrile biomechanical examination gloves, clinical glove evaluation is still needed to determine their performance in the health care setting. Tags: Comparative Study; Human Technicians; *Gloves, Protective; Descriptors: *Emergency Medical Biomechanics; Evaluation Studies; Gloves, Protective -- standards -- ST; Latex; Nitriles (Latex); 0 (Nitriles) CAS Registry No.: 0 Record Date Created: 19991223 Record Date Completed: 19991223 7/9/5 (Item 1 from file: 94) DIALOG(R) File 94: JICST-EPlus (c) 2004 Japan Science and Tech Corp(JST). All rts. reserv. JICST ACCESSION NUMBER: 93A0010265 FILE SEGMENT: JICST-E 01606578 Development of hand operation force display. SATO SHIGERU (1); SANO YOSHIMASA (1); KIKUCHI SUEHIKO (1); SHIMOJO MAKOTO (1); SAITO ICHIRO (1) (1) Industrial Products Res. Inst. Ningen Kogaku (Japanese Journal of Ergonomics), 1992, VOL.28, NO.5, PAGE.251-257, FIG.12, TBL.1, REF.11 JOURNAL NUMBER: S0258AAF ISSN NO: 0549-4974 UNIVERSAL DECIMAL CLASSIFICATION: 681.52 LANGUAGE: Japanese COUNTRY OF PUBLICATION: Japan DOCUMENT TYPE: Journal ARTICLE TYPE: Original paper MEDIA TYPE: Printed Publication ABSTRACT: A measuring system of hand operation force distribution has been developed. There was not any equipment for this purpose that is suitable for wide use. This system has glove type sensors which can on the hands as gloves . The force distribution data are be **put** shown on CRT display of personal computer as a color graphics. The system includes three parts. The first is the glove type sensor, the second is scanning circuit, and the third is personal computer as controller. The glove type sensor is constructed with pressure sensitive conductive rubber sheets and flexible print circuit. There are 81 force sensors in each hand, and they are connected in 7*15 array of matrix. Using this system, force distribution pattern of human hand operation can be observed. (author abst.) DESCRIPTORS: finger(body region); operation(processing); sensor; load(weight); measuring instrument; human engineering; distribution BROADER DESCRIPTORS: hand(body region); arm(forefoot); extremity; body region; instrumentation element; engineering

CLASSIFICATION CODE(S): IB01000S

(Item 1 from file: 350) 18/9/9 DIALOG(R) File 350: Derwent WPIX (c) 2004 Thomson Derwent. All rts. reserv. **Image available** 013121114 WPI Acc No: 2000-292985/200025 XRAM Acc No: C00-088518 XRPX Acc No: N00-219722 Testing forces experienced by wearer when donning stocking involves measuring force in advancing geometric body and extension of stocking secured to support and inserted with tension testing head Patent Assignee: BEIERSDORF-JOBST INC (BEIE) Inventor: LOVELESS J D; TUCKER D M; YAKOPSON S M; TUCKER K M Number of Countries: 021 Number of Patents: 007 Patent Family: Patent No Kind Date Applicat No Kind Date Week 20000406 WO 99US21676 WO 200018344 A1 Α 19990917 200025 AU 9964989 Α 20000417 AU 9964989 Α 19990917 200035 EP 1115359 A1 20010718 EP 99952937 Α 19990917 200142 WO 99US21676 Α 19990917 20020725 AU 9964989 200260 AU 750610 В Α 19990917 US 6578433 20030617 US 98101700 Ρ 19980925 200341 WO 99US21676 Α 19990917 US 2001787598 Α 20010320 EP 99952937 EP 1115359 B1 20030604 Α 19990917 200344 WO 99US21676 Α 19990917 DE 69908617 E 20030710 DE 608617 Α 19990917 200353 EP 99952937 Α 19990917 WO 99US21676 Α 19990917 Priority Applications (No Type Date): US 98101700 P 19980925; US 2001787598 A 20010320 Patent Details: Patent No Kind Lan Pg Main IPC Filing Notes WO 200018344 A1 E 18 A61F-013/08 Designated States (National): AU US Designated States (Regional): AT BE CH CY DE DK ES FI FR GB GR IE IT LU MC NL PT SE Based on patent WO 200018344 Α Al E A61F-013/08 Based on patent WO 200018344 Designated States (Regional): AT BE CH CY DE DK ES FI FR GB GR IE IT LI LU MC NL PT SE

AU 9964989 EP 1115359 AU 750610 A61F-013/08 Previous Publ. patent AU 9964989 Based on patent WO 200018344 US 6578433 B1 G01N-003/08 Provisional application US 98101700 Based on patent WO 200018344 A61F-013/08 B1 E Based on patent WO 200018344 EP 1115359 Designated States (Regional): AT BE CH CY DE DK ES FI FR GB GR IE IT LI LU MC NL PT SE DE 69908617 E A61F-013/08 Based on patent EP 1115359 Based on patent WO 200018344

Abstract (Basic): WO 200018344 A1

NOVELTY - Testing the forces experienced by a wearer when **donning** a stocking includes (a) securing an end of the stocking to a support; (b) inserting a tension testing head (15) within the stocking; (c) passing a geometric body of the head through the interior of the stocking; and (d) **measuring** the **force** used to advanced the geometric body and the extension of the stocking.

DETAILED DESCRIPTION - An INDEPENDENT CLAIM is also included for a

device used in testing the forces experienced by a wearer when donning a stocking (10). The device includes (a) a stocking support or a pin bar (11) to secure one end of the stocking; (b) a geometric body (16) attached to a rod (17) adapted to be pulled or pushed through the stocking; (c) a drive mechanism (18) to move the geometric body through the stocking; and (d) a tension measuring and recording device (20). USE - The invention is used for testing the forces experienced by a wearer when donning a stocking. It is particularly used for simulating and measuring frictional and compressive forces that a patient would experience when donning a stocking. ADVANTAGE - The invention provides valuable information which can be used in the design and comparison of products such as effects on donnability of various softeners and finishes, fiber selection, knit structure selection, and type of yarns and fibers to be used. The manufacturer can obtain concrete data with respect to whether a particular product is easier to don than the other. The effects of modifications to a product on the donning curve can also be readily evaluated. DESCRIPTION OF DRAWING(S) - The figure shows a testing device. Stocking (10) Stocking support or pin bar (11) Tension testing head (15) Geometric body (16) Rod (17) Drive mechanism (18) Tension measuring and recording device (20) pp; 18 DwgNo 1/4 Technology Focus: TECHNOLOGY FOCUS - MECHANICAL ENGINEERING - Preferred Method: The advancing step includes pushing and pulling the geometric body through the stocking or pulling the stocking over the geometric body. The method also includes recording the force used to advance the geometric body and the extension of the stocking. The geometric body is shaped to simulate a portion of a human foot. Title Terms: TEST; FORCE; EXPERIENCE; WEAR; DONNING; STOCKING; MEASURE; FORCE; ADVANCE; GEOMETRY; BODY; EXTEND; STOCKING; SECURE; SUPPORT; INSERT ; TENSION; TEST; HEAD Derwent Class: D22; F07; P32; S02 International Patent Class (Main): A61F-013/08; G01N-003/08 International Patent Class (Additional): G01L-005/00; G01M-019/00 File Segment: CPI; EPI; EngPI Manual Codes (CPI/A-N): D09-C04B; F03-K02; F04-C02; F04-E04 Manual Codes (EPI/S-X): S02-F03; S02-J09 18/9/10 (Item 1 from file: 95) DIALOG(R) File 95:TEME-Technology & Management (c) 2004 FIZ TECHNIK. All rts. reserv.

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Biomechanical performance of latex and non-latex double-glove systems (Ergebisse biomechanischer Untersuchungen von Latex-freien Doppelhandschuhen und solchen aus Latex) Fisher, MD; Reddy, VR; Williams, FM; Lin, KY; Thacker, JG; Edlich, RF Univ. of Virginia School of Medicine, Charlottesville, USA; Univ. of Virginia, Charlottesville, USA Journal of Biomedical Materials Research, v48, n6, pp797-806, 1999 Document type: journal article Language: English Record type: Abstract ISSN: 0021-9304

ABSTRACT:

The purpose of the study was to evaluate ten commercially available latex, powder-free surgical gloves and four commercially available non-latex, powder-free surgical gloves using standardized, reproducible biomechanical parameters that included glove thickness, puncture resistance, and glove donning force. For all gloves tested, with one exception (Neolon PF), puncture resistance increased for double-gloves as compared to single-gloves. In addition, single-gloves thickness was not a reliable determinant of puncture resistance for either latex or non-latex gloves. For the latex gloves, the Ultrafree double and single-gloves exhibited the highest puncture resistance. The glove donning forces for the Biogel M and Biogel Sensor single-gloves were the lowest. In contrast, the Biogel reveal and Encore Ultra-thick exhibited the lowest double-glove donning forces. On the basis of these performance tests of latex gloves, the surgeon should consider the Biogel Reveal as well as the Ultrafree gloves for their latex double-glove system. For the non-latex gloves, the Pure Advantage Nitrile glove had the highest puncture resistence for one layer and two layers of glove material. The thin Pure Advanatge Nitrile glove had low glove donning forces for both single-glove donning configurations and both double-glove donning configurations. Consequently, the authors recommend the Pure Advantage Nitrile glove as the powder-free, non-latex, double-glove system.

DESCRIPTORS: PROTECTIVE GLOVE; BIOMECHANICS; BIOCOMPATIBLE MATERIALS; PUNCTURE RESISTANCE; SURGEON S GOWN; FORCE MEASUREMENT IDENTIFIERS: Chirugenhandschuh; Biomechanik; Latex; Perforierwiderstand